

Modeling indirect interaction in multiagent systems

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Intelligence is interactive

- What kind of interaction is needed to act intelligently?
- *Example:* Mars rovers need not just to compute answers to questions, but to *adapt* to a changing environment.
- The interactive environment defines the problem.
- Intelligence is the ability to adapt in an interactive, changing environment.
- Our interest: intelligent behavior through *self-organization*, via *indirect interaction*, in *multiagent systems*

Five dimensions to classify environments

- accessible vs. inaccessible;
- deterministic vs. non-deterministic;
- episodic vs. nonepisodic;
- static vs. dynamic;
- discrete vs. continuous

(Russell-Norvig, 1995)

Adaptation

- Definition: learning that changes behavior
- The aim of behavior is to change one's environment in a favorable way
- Key type of environment:
 - *dynamic* (environment may change independently of agent)
 - *persistent* (environment's state is subject to change in response to agent)

Some interaction patterns in natural settings

1. Termites gathering chips

Move at random, pick up chip when encountered, put down when another found

2. Ants foraging for food

Ants leave chemical trail, prefer existing trails, blaze shorter and shorter trails to and from food

3. Slime mold dividing and aggregating

These amoeba may aggregate by emitting a chemical, migrating toward its greatest concentration

Self-organization and emergent behavior

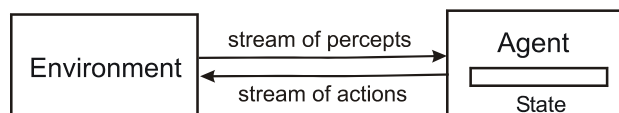
- *Definition:* **Self-organization** is the decentralized interaction of a set of processes or structures at a lower level of a system to yield global structures or behavior at a higher level
- *Example:* Chemical reactions
- *Contrast to:* Centralized, algorithmic behavior
- System behavior that is not the sum of component behaviors is called *emergent*

Stigmergy

- *Definition:* A variety of self-organization in which mobile agents interact via their shared environment
- *Contrast to:* direct interaction; centralized interaction
- *Examples:*
 - termites gathering chips,
 - ants foraging,
 - slime mold aggregation

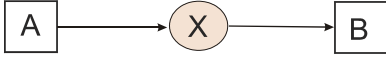
Sequential interaction

- *Definition:* An *interactive computation* is an ongoing exchange of data among computing agents, such that the output of each may causally influence its later inputs
- *Definition:* An *agent with persistent state* (APS) is an entity that accepts inputs, emits outputs, and has a *state* or *memory* whose value may change from one I/O step to the next



Indirect interaction

Defn: Interaction via persistent, observable state changes, in which the destination of output is any agent that observes these state changes

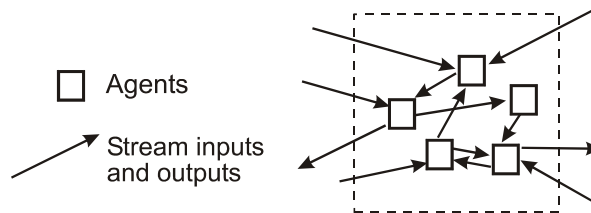
- Agents *A* and *B* (right) may interact with each other *indirectly* via shared variable *x*

- Features:
 - **anonymity** (recipient ID not used in access)
 - **time delay** (state changes persist)
 - **space decoupling** (agents *A*, *B* need not meet)

The power of persistence

- *Discussion:* It can be shown that computing agents with persistent state are capable of a wider range of behaviors than ones without persistent state
- *Example:* By remembering past answers, prosecutor may ask questions that force a witness to tell the truth or contradict self
- Persistence of environment is what enables termites, ants, slime mold to coordinate actions

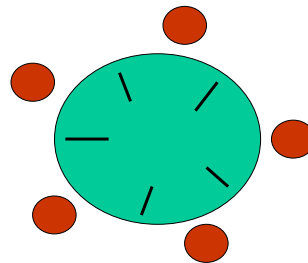
Multiagent interaction

- MAI is characterized by *multiple concurrent streams* of input/output, and by *creation/destruction* of these streams during a computation
- MAI is distinguished from *sequential interaction* and is more powerful



Dining Philosophers

- *Rule*: Philosophers sit in circle, with one chopstick between each pair
- *Activity of each*: Eat, think, eat, think...
- *Global goal*: coordinate to avoid starvation
- *Features of problem*:
 - Locality
 - Anonymity
 - Asynchrony
 - Non-intentionality
- Solution requires indirect interaction



Multiagent systems require indirect interaction

Theorem:

- *Let S be a multiagent system that contains agents and possibly shared variables that form a DPE w.r.t. the other agents.*
- *Then indirect interaction occurs in S .*

Significance: Since indirect interaction is an essential feature of multiagent systems, we must model this form of interaction

Proof

1. Let S be a multiagent system in which some subset of agents, and possibly shared variables, form a dynamic persistent environment with respect to the others.
2. Suppose S is characterized by direct interaction only.
3. A pair of agents in S interacts, by definition, only if each affects its own later inputs by its actions.
4. But because (2) rules out indirect interaction, no pair of agents in S communicates via state changes created by one and observable by the other in a common environment.
5. Hence no part of S has persistent state, hence no part can be a DPE w.r.t. the other part, contradicting (1). Hence (2) must be false.

References

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Additional ideas

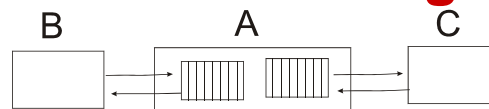
Difficult environments

- **Definition:** A class A of environments is *more difficult* than a class B , with respect to set S of adaptive agents, iff A 's range of observable behaviors is a strict superset of B 's.
- **Lemma:** The set of system behaviors observable in dynamic persistent environments strictly includes the set of behaviors observable in amnesic environments.

Indirect interaction and multiagent systems

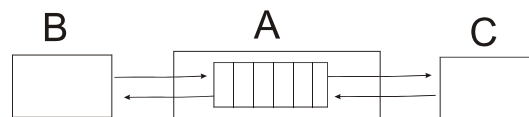
- In a MAS characterized by *locality* of interaction and *mobility* of agents, it is only possible for agents to influence overall system behavior by use of indirect interaction
- Richness of multiagent interaction:
 - It is due partly to ability of each agent to interact with multiple others
 - Hence each agent interacts indirectly with *all* others (otherwise system partitions)

Trivial vs. meaningful MAI



(b) *partitioned state*

- When agents *B* and *C* each interact with *A* via their own partitions of *A*'s state, they do not interact with each other (b).
- When *B* and *C* share access to the same memory in *A*, they interact, *indirectly* (a).



(a) *shared state*